

Real Time Drowsiness Identification Based On Eye State Analysis Using Enhanced CNN Algorithm

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ABSTRACT

Drowsiness among drivers is one of the leading causes of road accidents, resulting in severe injuries, fatalities, and economic losses world wide. To address this growing concern, this project presents a Real-time Drowsiness Identification Based On Eye State Analysis Using Artificial Intelligence and Machine Learning (AI/ML). The system captures live video frames of the driver through a camera and applies computer vision techniques to detect the face and eyes using OpenCV. The extracted eye regions are then analyzed by a trained convolutional neural network (CNN) model to classify the eye state as either open or closed. By continuously monitoring the driver's eye state over time, the system determines the onset of drowsiness when the eyes remain closed for a prolonged duration. Once drowsiness is detected, an audio-visual alert is triggered to prompt the driver to regain alertness. The proposed system aims to reduce accident risks by providing a low-cost, non-intrusive, and efficient solution that can be integrated into vehicles or used as a standalone safety device. Experimental results demonstrate that the AI/ML model achieves high accuracy in distinguishing between open and closed eye states, making it an effective tool for real-time driver monitoring and road safety enhancement.

Keywords: Driver drowsiness detection, Eye state analysis, Real-time monitoring, Computer vision, Artificial intelligence (AI), Machine learning (ML), Convolutional neural network (CNN), OpenCV, Face and eye detection, Road safety, Accident prevention, Audio-visual alert system

I. INTRODUCTION

1.1 ARTIFICIAL INTELLIGENCE AND MACHINE LEARNING

Artificial Intelligence (AI) and Machine Learning (ML) are rapidly transforming modern technology by enabling systems to human intelligence and learn from data. AI refers to the simulation of human-like intelligence in machines that can perform tasks such as reasoning, problem-solving, perception, and decision-making.

Machine Learning, a subset of AI, allows computers to automatically learn and improve from experience without being explicitly programmed. In the context of drowsiness detection, AI and ML techniques are used to analyze visual cues—such as eye movement, blinking patterns, and facial expressions—to determine a person's state of alertness. By training models on large datasets of eye images, ML algorithms can accurately distinguish between open and closed eye states, thereby identifying signs of fatigue. These technologies play a crucial role in enhancing safety systems in vehicles, workplaces, and other environments where human attentiveness is critical.[1]

With the rapid growth of deep learning techniques, AI and ML have become central to the development of intelligent drowsiness detection systems. Among various learning models, Convolutional Neural Networks (CNNs) have shown remarkable performance in visual recognition tasks due to their ability to automatically extract spatial and

temporal features from image data. In drowsiness detection applications, CNN-based models analyze eye-related features such as eyelid closure, blink duration, and eye aspect ratio to reliably assess alertness levels. These data-driven approaches eliminate the need for manual feature extraction, improving accuracy and robustness in real-world driving conditions.

Furthermore, AI- and ML-based drowsiness detection systems enable real-time monitoring and adaptive decision-making, which are essential for safety-critical environments. By continuously analyzing live video streams, ML models can detect subtle changes in driver behavior that indicate fatigue and trigger timely warning mechanisms. Compared to traditional rule-based or sensor-dependent methods, AI-driven solutions offer greater flexibility, scalability, and ease of deployment. As a result, the integration of AI and ML into driver monitoring systems plays a vital role in reducing fatigue-related accidents and enhancing overall safety in transportation and other attention-sensitive domains.[2]

Recent advancements in Artificial Intelligence and Machine Learning, particularly in the field of computer vision, have significantly enhanced the performance of drowsiness detection systems. Deep learning models, especially **Convolutional Neural Networks (CNNs)**, are widely used for analyzing visual information due to their ability to automatically extract meaningful features from image data.

In driver monitoring applications, CNNs process eye and

facial images to capture patterns related to eye closure, blink frequency, and facial behavior, enabling accurate classification of alert and drowsy states under diverse lighting and environmental conditions. Moreover, AI- and ML-based approaches enable real-time and non-intrusive monitoring, which is essential for safety-critical applications. By continuously analyzing live video streams, these systems can detect early signs of fatigue and issue timely warnings to prevent accidents. Compared to traditional sensor-based or manual monitoring methods, vision-based AI systems offer improved scalability, reduced hardware dependency, and higher adaptability to real-world scenarios. Consequently, the integration of AI and ML into drowsiness detection frameworks plays a vital role in improving reliability, responsiveness, and overall effectiveness of modern safety systems in transportation and other attention-dependent environments.[3]

II. RELATED WORKS

Reference[1]-The authors proposed a real-time drowsiness detection system based on eye state analysis using computer vision techniques. Initially, the face and eye regions are detected from live video streams using Haar Cascade classifiers. The extracted eye regions are then processed to obtain features related to eye openness.

A Support Vector Machine (SVM) classifier is employed to classify the eye state as open or closed. The system evaluates performance using confusion matrix metrics such as true positive, true negative, false positive, and false negative values. Experimental results show that the proposed model achieves high accuracy in controlled environments. The system is capable of operating in real time with minimal latency.

However, performance decreases under varying illumination and rapid head movements. The authors concluded that robustness needs improvement for real-world driving scenarios.

Reference[2]- In this study, the authors developed a deep learning-based drowsiness detection model using Convolutional Neural Networks (CNNs). The model directly learns

Reference [5] - In this research, the authors proposed a machine learning approach using Histogram of Oriented

discriminative features from eye images, eliminating the need for manual feature extraction. Preprocessing steps include normalization and data augmentation to improve generalization. The trained CNN classifies eye states in real time to detect prolonged eye closure. The system was evaluated using accuracy, precision, recall, and confusion matrix values. Experimental results demonstrated high detection accuracy and low false negative rates. The model performs well in diverse facial expressions. However, the authors noted that CNN training requires large labeled datasets. High computational resources also limit deployment on embedded systems.

Reference[3]-The authors presented a hybrid CNN-LSTM framework for real-time drowsiness identification. The CNN component extracts spatial features from eye images captured over time. The LSTM network analyzes temporal dependencies to detect continuous eye closure patterns. This approach improves the detection of drowsiness compared to frame-by-frame classification. The system was tested using precision, recall, and AUC metrics. Results indicated improved temporal stability and reduced false alarms. The model effectively captures blinking behavior and eye closure duration. However, the authors observed sensitivity to eye occlusion caused by glasses. Environmental lighting variation also affected model accuracy.

Reference[4] - This work proposed a real-time drowsiness detection method using the Eye Aspect Ratio (EAR). Facial landmarks are first detected to identify eye key points. EAR is calculated to measure the degree of eye openness. If the EAR value remains below a predefined threshold for a specific duration, the system identifies the driver as drowsy. The approach is computationally efficient and suitable for real-time applications.

Performance evaluation was conducted using sensitivity and specificity measures. The system demonstrated reliable detection under normal conditions. However, inaccuracies were observed during extreme head rotations. The authors suggested improving landmark detection for better robustness. Gradients (HOG) features and a Random Forest classifier. Eye regions are extracted from facial images before

feature computation. HOG descriptors capture edge and shape information of the eye region. These features are then classified using the Random Forest algorithm. The model was evaluated using accuracy and confusion matrix metrics. Results indicated stable performance under controlled conditions. The system is computationally less intensive compared to deep learning methods. Detection model using SVM, k-However, handcrafted features limited adaptability to diverse datasets. The authors concluded that deep learning could offer better generalization.

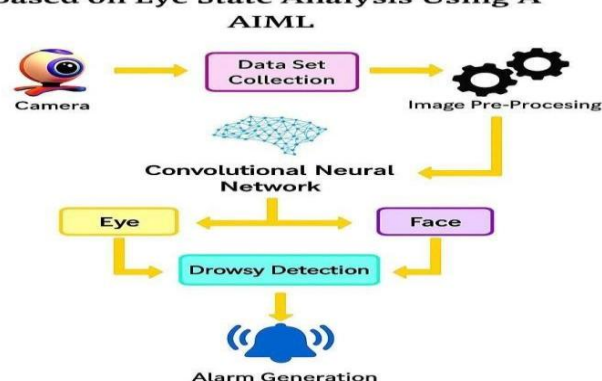
Reference [6] - The authors proposed a multi-feature drowsiness detection system integrating eye closure, blink rate, and head pose estimation. Feature normalization and noise filtering are applied during preprocessing. Machine learning classifiers such as SVM are used to classify the driver's state. The system improves detection accuracy by combining multiple behavioral cues. Performance evaluation showed robustness under moderate lighting variations. The approach reduced false positives compared to single-feature systems. However, increased computational cost was observed due to multiple feature extraction modules. Real-time performance may be affected on low-end hardware. The authors suggested optimizing feature selection.

Reference [7] - This study presented an ensemble-based drowsiness NN, and Naïve Bayes classifiers. Eye state features extracted from facial landmarks are fed into individual classifiers. The final decision is made using majority voting among classifiers. The ensemble approach improves classification accuracy and reduces false alarms. Performance was evaluated using true positive and false positive rates. The model demonstrated better reliability compared to standalone classifiers. However, system complexity increased due to multiple models. Processing time also increased slightly. The authors recommended balancing accuracy and computational efficiency.

Reference [8] - The authors developed a and closed eyes is used —sourced from

lightweight real-time drowsiness detection method using Eye Aspect Ratio (EAR) combined with temporal smoothing. Temporal filtering reduces sudden fluctuations in EAR values. This improves stability and reduces false detections. The system was tested on multiple subjects under different conditions. Performance metrics included sensitivity, specificity, and accuracy. Results showed fast response and reliable detection. The system is suitable for real-time applications.

However, it struggled with eye occlusion caused by glasses. Sunglasses further degraded detection accuracy. The **Real-Time Drowsiness Identification Based on Eye State Analysis Using A**



authors suggested integrating additional features for robustness.

III. PROPOSED METHODOLOGY

Figure1: Proposed System Architecture

The proposed system eliminates the drawbacks of existing methods by implementing an **AI and ML-based real-time eye state analysis approach**. The system captures live video through a webcam, detects the driver's face and eyes using **Haar Cascade classifiers**, and passes the cropped eye images to a **Convolutional Neural Network (CNN)** model trained to classify eyes as "open" or "closed." When the system detects continuous closed-eye frames for a certain period, it activates an **alert mechanism** (sound alarm) to notify the driver. The proposed design is **non-intrusive, fully automated, and reliable**, offering consistent performance under different real-world conditions.

DATA ACQUISITION AND PREPROCESSING

This module is responsible for collecting and preparing data for model training. A dataset containing thousands of images of open public datasets or captured manually under varied conditions. Preprocessing

ensures uniformity and quality by converting images to grayscale, resizing them (e.g., 24×24 or 32×32 pixels), and normalizing pixel values between 0 and 1. To improve model generalization, **data augmentation** techniques such as rotation, flipping, zooming, and brightness adjustment are applied. This process helps the CNN model learn diverse eye patterns and improves accuracy under different lighting or facial orientations.

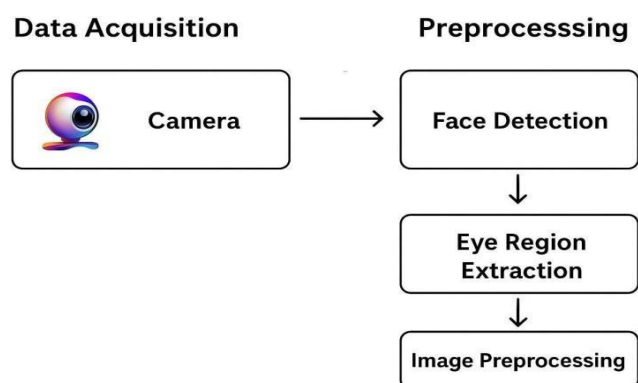


FIGURE 2: DATA ACQUISITION AND PREPROCESSING DIAGRAM

PROPOSED ALGORITHM

The proposed algorithm for real-time drowsiness detection is designed to continuously monitor the user's eye state and trigger an alert when prolonged eye closure is detected. It combines computer vision for face and eye detection with machine learning for classification. The major steps of the algorithm are as follows:

Step 1: Start Video Capture

The system initializes the camera to continuously capture real-time video frames.

Step 2: Face and Eye Detection

Using the **Haar Cascade Classifier**, the system detects the driver's face and localizes the eye regions from each captured frame.

Step 3: Preprocessing of Eye Images The detected eye regions are cropped, converted to grayscale, and resized to the required input size for the CNN model (e.g., 24×24).

Step 4: Eye State Prediction (Using CNN)

The preprocessed eye image is passed to the trained CNN model, which predicts whether the eyes are **open (1)** or **closed (0)**.

Step 5: Drowsiness Detection Logic

A counter keeps track of consecutive closed-eye frames. If eyes remain closed beyond a predefined frame threshold (e.g., 30 frames ~ 2 seconds), the system identifies the user as drowsy.

Step 6: Alert Activation

Once drowsiness is detected, the **alarm module** is activated through the Pygame library to play an alert sound, waking the driver.

Step 7: Continuous Monitoring After the alert, the system resets the counter and continues real-time monitoring of eye states until the program is manually stopped.

FLOW DIAGRAM OF THE SYSTEM

The flow diagram illustrates the step-by-step operational flow of the system, showing the logical sequence of operations from capturing video frames to issuing an alert.

Step 1: Start the Camera and Capture Real-Time Video

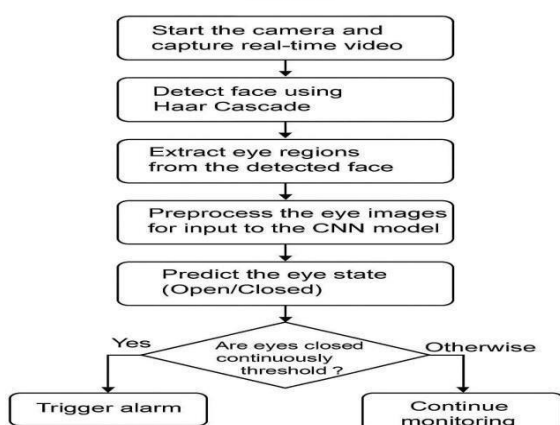
This step initializes the system by activating the camera to capture live video frames. The camera continuously records the driver's facial movements in real time. Captured video is converted into individual frames for further processing. Each frame serves as an input image for the detection pipeline. Real-time capture ensures immediate detection of drowsiness behavior. Frame rate consistency is important to avoid missing critical eye movements. This step enables continuous monitoring without user intervention. Any delay at this stage may reduce system responsiveness.

Step 2: Detect Face Using Haar Cascade

In this step, the Haar Cascade classifier is used to detect the face region. The algorithm scans each frame to identify facial patterns.

It uses pretrained features to detect faces efficiently. Face detection reduces unnecessary processing of background regions. Only frames with detected faces proceed to the next step. This improves system accuracy and computational efficiency. Haar Cascade works well in real-

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time applications. However, extreme lighting variations may affect detection accuracy

Step3: Extract Eye Regions from the Detected Face

Once the face is detected, the eye regions are localized within the face area. This step focuses only on the upper facial region where eyes are present. Eye region extraction reduces noise from irrelevant facial features. Accurate extraction is critical for reliable eye state classification. Bounding boxes are used to crop left and right eye images. This step improves model performance by focusing on relevant data. It also reduces computational load on the CNN. Incorrect eye extraction may lead to misclassification.

Step4: Preprocess the Eye Images for CNN Input

Preprocessing prepares eye images for CNN-based classification. Images are resized to a fixed dimension required by the model. Normalization is applied to scale pixel values consistently. Noise reduction techniques may be used to improve clarity. Grayscale conversion can be applied to reduce complexity. Data formatting ensures compatibility with the CNN architecture. This step enhances model accuracy and stability. Poor preprocessing can negatively affect prediction results.

Step5: Predict the Eye State (Open/Closed)

The preprocessed eye images are passed to the trained CNN model. The CNN extracts deep features from the eye images. Based on learned

patterns, the model classifies eyes as open or closed.

Prediction is performed for every frame in real time.

Probability scores help determine classification confidence.

This step is crucial for identifying drowsiness indicators.

High accuracy is essential to avoid false alerts. The output is forwarded to the decision-making module.

Step6: Check Continuous Eye Closure Threshold

In this step, the system checks if the eyes remain closed continuously. A predefined time or frame threshold is used for evaluation. Short blinks are ignored to prevent false detection.

Prolonged eye closure indicates possible drowsiness.

This temporal analysis improves reliability over single-frame decisions. The system tracks eye state history across frames.

Threshold selection directly affects system sensitivity.

Incorrect thresholds may cause false alarms or missed detections.

Step7: Trigger Alarm

If continuous eye closure exceeds the threshold, an alarm is triggered. The alarm alerts the driver about detected drowsiness. Audio or visual alerts are commonly used. This step aims

to prevent accidents by waking the driver. Immediate alert generation is critical for safety. The alarm continues until eye activity resumes. This step

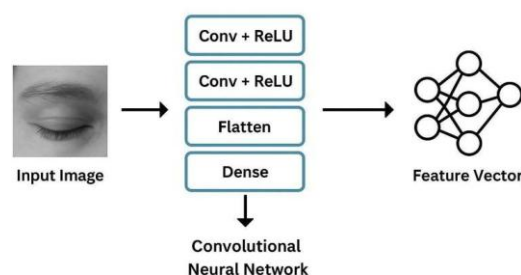
represents the system's preventive action. Effectiveness depends on timely and accurate detection.

Step8: Continue Monitoring

If the eyes are not continuously closed, monitoring continues. The system keeps processing incoming video frames. Eye state is continuously analyzed without interruption. This ensures long-term real-time surveillance of the driver. No alert is generated during normal eye activity. System performance remains stable during

continuous operation. This step enables uninterrupted detection throughout the journey. Monitoring stops on

CNN Development and Feature Extraction



ly when the system is manually terminated.

In this proposed system, an enhanced Convolutional Neural Network (CNN) is utilized to perform efficient feature extraction from eye-region images for real-time drowsiness detection. The model automatically learns discriminative spatial features such as eyelid contours, eye closure patterns, and texture variations without the need for manual feature engineering. By employing multiple convolutional layers with optimized kernel sizes and activation functions, the network captures both low-level features (edges and shapes) and high-level representations (eye-state patterns), enabling accurate classification of open and closed eye states.

To further improve feature extraction capability, advanced techniques such as batch normalization and pooling strategies are integrated to enhance feature stability and reduce noise. The enhanced CNN also incorporates data augmentation to ensure robustness against variations in lighting, head pose, and occlusions like glasses. This results in a more generalized feature representation, allowing the system to maintain consistent performance in real-world driving conditions and making it suitable for deployment in intelligent driver monitoring applications.

1. Project Overview-Real-

Time Drowsiness Detection is an intelligent system designed to improve road safety by monitoring a driver's alertness level. The project uses Artificial Intelligence and Machine Learning techniques to automatically detect signs of fatigue. Driver drowsiness is one of the major causes of road accidents worldwide. The system continuously observes facial features such as eyes and eyelids. A Convolutional Neural Network (CNN) is used as the core model. CNNs are well-suited for image-based analysis tasks. The system does not require manual feature extraction. It learns important features directly from facial images. The model works in real time while the vehicle is in motion. This helps in preventing accidents by giving early warnings.

2. Input Image Acquisition - Input image acquisition is the first step in the system. A camera is installed facing the driver inside the vehicle. The camera captures real-time video of the driver's face. Video frames are extracted at regular intervals. These frames serve as input images for the CNN model. The eye or face

Enhanced CNN-Based Algorithm

region is selected for analysis. Real-time capture ensures continuous monitoring. It allows the system to detect fatigue instantly. Good image quality improves detection accuracy. This step forms the foundation of the entire system.

3. CNN Development - CNN development involves designing layers for image analysis. The network is structured with convolution, activation, and dense layers. CNN automatically learns features from raw images. Manual feature engineering is not required. The architecture is optimized for eye and face images. Multiple layers help in learning hierarchical features. Early layers learn simple features. Deeper layers learn complex patterns. The CNN is trained using labeled datasets. A trained CNN performs accurate drowsiness detection.

1. First Convolution+ReLU Layer - The first convolution layer processes the input image. It applies filters to detect low-level features. Edges and contours of the eyes are identified. Basic shape and textures are captured. This layer focuses on visual structure. ReLU activation is applied after convolution. ReLU removes negative pixel values. It introduces non-linearity to the model. This improves learning efficiency. The output is a set of feature maps.

2. Second Convolution+ReLU Layer - The second convolution layer builds on previous features. It analyzes the feature maps from the first layer. This layer detects more meaningful patterns. Eye closure and blinking behavior are identified. Eyelid movement patterns are learned. These features are critical for drowsiness detection. ReLU activation improves feature clarity. The model becomes more robust at this stage. Complex facial patterns are recognized. The output is refined feature maps.

3. ReLU Activation Function - ReLU stands for Rectified Linear Unit. It replaces negative values with zero. Positive values remain unchanged. This helps the network learn faster. ReLU avoids the vanishing gradient problem. It improves training efficiency. The function adds non-linearity to the model. This enables learning of complex patterns. ReLU is computationally simple. It is widely used in CNN architectures.

4. Feature Extraction - Feature extraction is a key process in CNN. It is performed automatically by convolution layers. Important visual information is

captured. Eye shape and eye state are learned. Blink duration is analyzed. Extracted features are stored as feature maps. Feature maps represent learned patterns. These patterns distinguish

5. This improves accuracy and reliability.

6. **Flatten Layer** - The Flatten layer reshapes the data. It converts feature maps into a single vector. Spatial information is transformed into numerical form. This step prepares data for classification. Flattening does not lose important features. It organizes extracted features efficiently. Dense layers require 1D input. Flatten acts as a bridge between layers. It simplifies further processing. This step is essential for decision-making.

4. **Dense Layer** -

The Dense layer is fully connected. Each neuron is connected to all inputs. It analyzes the flattened feature vector. Relationships between features are learned. The layer combines all extracted information. It helps in decision-making. Weights are adjusted during training. The Dense layer improves classification accuracy. It produces the final output values. This layer determines alertness level.

5. **Drowsiness Classification** - Drowsiness classification is the final step. The model analyzes the feature vector. It predicts whether the driver is alert or drowsy. Binary or multi-class classification is used. Probability values may be generated. A threshold determines the final decision. If drowsy, an alert can be triggered. Real-time response improves safety. The system works continuously. This helps reduce accidents caused by fatigue.

Conclusion

This project presents a real-time drowsiness detection system based on eye-state analysis using an enhanced Convolutional Neural Network (CNN) integrated with AI and ML techniques. The proposed model effectively identifies eye closure patterns and classifies driver alertness with high accuracy. By leveraging improved feature extraction and optimized network architecture, the system is capable of operating efficiently in real-time environments, making it suitable for practical driver monitoring applications.

The implementation demonstrates the ability of the enhanced CNN model to handle variations such as lighting conditions, facial features, and minor occlusions. The system's performance highlights its reliability in detecting early signs of driver fatigue, thereby contributing to accident prevention and road safety. Additionally, the model's design ensures a

h alert and drowsy states. No manual feature selection is needed.

balance between computational efficiency and detection accuracy, which is essential for real-time deployment. Overall, this work establishes a strong foundation for intelligent drowsiness detection systems. With the planned integration of cloud technologies and further enhancements, the system can be scaled for broader applications such as fleet management and smart transportation. The proposed approach shows significant potential in advancing AI-driven safety solutions in real-world scenarios.

Proposed System Output

The proposed system outputs real-time drowsiness detection results by analyzing the driver's eye state using an enhanced CNN model integrated with OpenCV. It continuously captures video input, processes the eye region, and classifies whether the eyes are open or closed. If the system detects prolonged eye closure indicating drowsiness, it immediately generates an alert such as an alarm to notify the driver. When the eyes are open, the system continues monitoring without interruption. This real-time output ensures timely detection and alerting, thereby



improving driver safety and preventing potential accidents

Future Work

In future work, the proposed real-time drowsiness detection system can be extended by integrating cloud computing technologies to enable scalable and centralized monitoring. By connecting the enhanced CNN model with cloud platforms, real-time data collected from in-vehicle cameras can be transmitted, stored, and processed efficiently. This will allow the system to support multiple users simultaneously and enable large-scale deployment in applications such as fleet management and smart transportation systems.

Cloud integration will also facilitate continuous model datasets from different users and environments, the system can enhance its accuracy and adaptability to real-world conditions. Additionally, cloud-based dashboards can be developed to provide real-time status updates, alerts, and historical analytics, enabling remote monitoring by authorities or management systems.

Furthermore, the combination of cloud computing with edge devices can be explored to achieve a hybrid architecture. In this approach, initial processing and detection can be performed locally on edge devices for low latency, while the cloud handles data storage, advanced analytics, and model updates. This balance between edge and cloud computing can improve system efficiency, reduce response time, and optimize resource utilization. Finally, future work will also focus on implementing secure data transmission and privacy-preserving techniques in cloud communication. Ensuring data encryption, user authentication, and compliance with data protection standards will be essential for real-world deployment. These enhancements will make the system more reliable, scalable, and suitable for integration into next-generation intelligent transportation and safety systems.

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